# **Safety Manual**

# **VEGATOR 121, 122**

With SIL qualification



Document ID: 49221





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### 1 Document language

DE	Das vorliegende <i>Safety Manual</i> für Funktionale Sicherheit ist verfügbar in den Sprachen Deutsch, Englisch, Französisch und Russisch.
EN	The current <i>Safety Manual</i> for Functional Safety is available in German, English, French and Russian language.
FR	Le présent <i>Safety Manual</i> de sécurité fonctionnelle est disponible dans les langues suivantes: allemand, anglais, français et russe.
RU	Данное руководство по функциональной безопасности Safety Manual имеется на немецком, английском, французском и русском языках.



### 2 Scope

#### 2.1 Instrument version

This safety manual applies to controllers

**VEGATOR 121, 122** 

Input signal:

8/16 mA

Valid version:

• from HW Ver 1.1.0

### 2.2 Application area

The controllers can be used with a suitable transducer for level detection or range monitoring in a safety-related system in accordance with IEC 61508 in the *low demand mode* or *high demand mode*.

Due to the systematic capability SC3 this is possible:

- Up to SIL2 in single-channel architecture
- Up to SIL3 in a multiple-channel architecture (systematic suitability SC3)

The following interface can be used to output the measured value:

- VEGATOR 121: relay 1
- VEGATOR 122: relay 1 or relay 2

The NO contacts must be used!1)



For the execution of a safety function in safety-relevant applications, the use of the following functions is restricted or not possible:

#### VEGATOR 121.\*\*S

Relay 2 is only permitted for informative use. The following options are possible:

- Relay 2 as fail safe relay (e.g. information on the device status with the proof test)
- Relay 2 as second function relay with identical behaviour as relay 1, however not for safety-relevant purposes

#### VEGATOR 122

- The two-point control mode is not accepted
- Only one of the two channels must be used to realized a redundant SIL3 architecture

#### 2.3 SIL conformity

The SIL conformity was independently judged and certified by the  $T\ddot{U}V$  Rheinland according to IEC 61508:2010 (Ed.2).<sup>2)</sup>



The certificate is valid for the entire service life of all instruments that were sold before the certificate expired!

- <sup>1)</sup> NO = Normal Open
- 2) Verification documents see appendix





	3 Planning
	3.1 Safety function
Level detection with VEGATOR 121 or 122	The transducer fed by the controller generates a signal of > 12 mA or < 12 mA corresponding to the process variable. A level detection relay is switched dependent on this signal and on the selected mode.
	This applies for both channels in the VEGATOR 122 version if the two- point control is not selected.
Range monitoring with VEGATOR 122	Two transducers fed by the controller each generates a signal of > 12 mA or < 12 mA corresponding to the process variable. Two limit values can therefore be measured for range monitoring.
	The following points must be observed here:
	The two NO contacts must be connected in series
	<ul> <li>Channel for the upper limit: Max. mode</li> <li>Channel for the lower limit: Min. mode</li> </ul>
	The two-point control may not be selected
	3.2 Safe state
Safe state	The safe condition of the output is independent of the mode, by defini- tion the currentless state of the relay (quiescent current principle).
	Therefore only the NO contact may be used for safety-relevant applications.
Fault signals in case of	Relay outputs:
malfunction	NO contacts open
	3.3 Prerequisites for operation
Instructions and restric- tions	• The measuring system should suit the application. The application- specific limits must be maintained
	<ul> <li>The specifications according to the operating instructions manual, particularly the current load on the output circuits, must be kept within the specified limits</li> </ul>
	<ul> <li>To avoid a fusing of the relay contacts, these must be protected by an external fuse that triggers at 60 % of the max. contact current load.</li> </ul>
	<ul> <li>The installation site must comply with IP 54 protection</li> </ul>
	<ul> <li>The instructions in chapter "Safety-related characteristics", para- graph "Supplementary information" must be noted</li> </ul>
	<ul> <li>All parts of the measuring chain must correspond to the planned "Safety Integrity Level (SIL)"</li> </ul>



### 4 Safety-related characteristics

# 4.1 Characteristics in accordance with IEC 61508 for level detection

VEGATOR 121 or one channel of the VEGATOR 122

Parameter	Value
Safety Integrity Level	SIL2 in single-channel architecture
	SIL3 in multiple channel architecture <sup>3)</sup>
Hardware fault tolerance	HFT = 0
Instrument type	Туре А
Mode	Low demand mode, High demand mode
SFF	> 60 %
MTBF <sup>4)</sup>	1.33 x 10 <sup>6</sup> h (152 years)
Fault reaction time5)	< 2 s

#### Failure rates

λ <sub>s</sub>	$\lambda_{_{DD}}$	$\lambda_{DU}$	λ <sub>H</sub>	λ	$\lambda_{AD}$
242 FIT	30 FIT	49 FIT	0 FIT	0 FIT	0 FIT
PFD <sub>AVG</sub>		0.041 x 10 <sup>-2</sup>		(T1 = 1 year)	
PFD <sub>AVG</sub>		0.060 x 10 <sup>-2</sup>		(T1 = 2 years	3)
PFD <sub>AVG</sub>		0.118 x 10 <sup>-2</sup>		(T1 = 5 years)	
PFH		0.049 x 10 <sup>-6</sup> 1/h			

#### Proof Test Coverag (PTC)

Test type <sup>6)</sup>	Remaining failure rate of dangerous unde- tected failures	РТС
Test 1	4 FIT	91 %
Test 2 and 3	2 FIT	96 %

### 4.2 Characteristics in accordance with IEC 61508 for range monitoring

#### VEGATOR 122

Parameter	Value
Safety Integrity Level	SIL2 in single-channel architecture
	SIL3 in multiple channel architecture7)

- <sup>3)</sup> Homogeneous redundancy possible (see note in the section "Area of Applicaton").
- <sup>4)</sup> Including errors outside the safety function.
- <sup>5)</sup> Time between the occurrence of the event and the output of a fault signal.
- <sup>6)</sup> See section "Proof test".
- 7) Homogeneous redundancy possible.



Parameter	Value
Hardware fault tolerance	HFT = 0
Instrument type	Туре А
Mode	Low demand mode, High demand mode
SFF	> 60 %
MTBF <sup>8)</sup>	1.15 x 10 <sup>6</sup> h (131 years)
Fault reaction time9)	<2s

#### Failure rates

λ <sub>s</sub>	$\lambda_{_{DD}}$	$\lambda_{DU}$	λ <sub>H</sub>	λ	$\lambda_{AD}$
323 FIT	45 FIT	79 FIT	0 FIT	0 FIT	0 FIT

PFD <sub>AVG</sub>	0.066 x 10 <sup>-2</sup>	(T1 = 1 year)
PFD <sub>AVG</sub>	0.097 x 10 <sup>-2</sup>	(T1 = 2 years)
PFD <sub>AVG</sub>	0.191 x 10 <sup>-2</sup>	(T1 = 5 years)
PFH	0.079 x 10 <sup>-6</sup> 1/h	

#### Proof Test Coverag (PTC)

Test type <sup>10)</sup>	Remaining failure rate of dangerous unde- tected failures	РТС
Test 1	7 FIT	91 %
Test 2 and 3	2 FIT	97 %

#### 4.3 Characteristics acc. to ISO 13849-1

Derived from the safety-related characteristics, the following figures result according to ISO 13849-1 (safety of machinery):<sup>11)</sup>

#### Level detection with VEGATOR 121 or one channel of the VEGATOR 122

# Range monitoring with VEGATOR 122

Parameter	Value
MTTFd	1437 years
DC	38 %
Performance Level	4.90 x 10 <sup>-8</sup> 1/h

Parameter	Value
MTTFd	916 years
DC	36 %
Performance Level	7.93 x 10 <sup>-8</sup> 1/h

<sup>8)</sup> Including errors outside the safety function.

<sup>9)</sup> Time between the occurrence of the event and the output of a fault signal.

<sup>10)</sup> See section "Proof test".

<sup>11)</sup> ISO 13849-1 was not part of the certification of the instrument.



	4.4	Supplementary information		
Determination of the failure rates	accord	lure rates of the instruments were determined by an FMEDA ling to IEC 61508. The calculations are based on failure rates of mponents according to <b>SN 29500</b> :		
	during	res refer to an average ambient temperature of 40 $^{\circ}$ C (104 $^{\circ}$ F) the operating time. For higher temperatures, the values should rected:		
		ntinuous application temperature > 50 °C (122 °F) by factor 1.3 ntinuous application temperature > 60 °C (140 °F) by factor 2.5		
	Simila	r factors apply if frequent temperature fluctations are expected.		
Assumptions of the FMEDA	the Mu We Fail The env	e failure rates are constant. Take note of the useful service life of components according to IEC 61508-2. Itiple failures are not taken into account ar on mechanical parts is not taken into account lure rates of external power supplies are not taken into account e environmental conditions correspond to an average industrial rironment avoid a fusing of the relay contacts, these must be protected by external fuse		
Calculation of PFD <sub>AVG</sub>	The va 1oo1 a	lues for $PFD_{AVG}$ specified above were calculated as follows for a architecture:		
	PFD/	$AVG = \frac{PTC \times \lambda_{DU} \times T1}{2} + \lambda_{DD} \times MTTR + \frac{(1 - PTC) \times \lambda_{DU} \times LT}{2}$		
	Param	eters used:		
		= Proof Test Interval		
	• LT :	C = 90 % = 10 years TR = 8 h		
Boundary conditions relating to transmitters		ansmitter used, must output an error current if it is powered by a e outside its voltage range.		
Multiple channel archi- tecture	Due to the systematic capability SC3, this instrument can also be used in multiple channel systems up to SIL3, also with a homogene- ously redundant configuration.			
	the sel rates. I	fety-related characteristics must be calculated especially for ected structure of the measuring chain using the stated failure n doing this, a suitable Common Cause Factor (CCF) must be ered (see IEC 61508-6, appendix D).		



### 5 Setup

#### 5.1 General information

Mounting and installation

Take note of the mounting and installation instructions in the operating instructions manual.

Setup must be carried out under process conditions.

#### 5.2 Adjustment instructions

Adjustment elements

The operating elements must be set according to the application. The function of the operating elements as well as the parameter adjustment procedure are described in the operating instructions.



During adjustment process, the safety function must be considered as unreliable!

If necessary, you must take other measures to maintain the safety function.



With regard to the switch on/swich off delay it must be ensured that the sum of all switching delays from the transducer to the actuator is adapted to the process safety time!



The instrument must be protected against inadvertent or unauthorized adjustment!



### 6 Diagnostics and servicing

#### 6.1 Behaviour in case of failure

 Internal diagnosis
 The instrument permanently monitored by an internal diagnostic system. If a malfunction is detected, a fault signal will be output on the safety-relevant output (see section "Safe status").

 The fault reaction time is specified in chapter "Safety-relevant characteristics".

 Error messages in case of malfunction

 The occurrence of an error is signalled by the red LED and, if necessary, by the fail safe relay.

 If failures are detected, the entire measuring system must be shut down and the process held in a safe state by other measures. The manufacturer must be informed of the occurrence of a dangerous undetected failure (incl. fault description).

### 6.2 Repair

Defective instruments can only be repaired by the manufacturer.



### 7 Proof test

### 7.1 General information

Objective	To identify possible dangerous, undetected failures, the safety func- tion must be checked by a proof test at adequate intervals. It is the user's responsibility to choose the type of testing. The time intervals are determined by the selected PFD <sub>AVG</sub> (see chapter "Safety-related characteristics").
	For documentation of these tests, the test protocol in the appendix can be used.
	If one of the tests proves negative, the entire measuring system must be switched out of service and the process held in a safe state by means of other measures.
	In a multiple channel architecture this applies separately to each channel.
Preparation	<ul> <li>Determine safety function (mode, switching points)</li> <li>If necessary, remove the instruments from the safety chain and maintain the safety function by other means</li> </ul>
Unsafe device status	Warning: During the function test, the safety function must be treated as unreli- able. Take into account that the function test influences downstream connected devices.
	If necessary, you must take other measures to maintain the safety function.
	After the function test, the status specified for the safety function must be restored.
	7.2 Test 1: Without input current simulation
Conditions	<ul> <li>Use of any transducer</li> <li>Output signals correspond to the current limit level</li> </ul>
Procedure	<ol> <li>Push the min./max. switch on the VEGATOR 121, 122</li> <li>Check relay contacts</li> </ol>
Expected result	<ul> <li>about 1: Relay and LED display change status</li> <li>about 2: Relay contacts open and close according to item 1</li> </ul>
Proof Test Coverage	See Safety-related characteristics
	7.3 Test 2: With input current simulation
Conditions	<ul><li>Possibility of sensor current simulation exists</li><li>Output signals correspond to the current limit level</li></ul>
Procedure	<ol> <li>Invert sensor current by means of the min./max. switch on the transducer (8 mA/16 mA)</li> <li>Check relation contents</li> </ol>
	2. Check relay contacts
Expected result	<ul> <li>about 1: State of relay and LED display follow the simulated sen- sor current</li> </ul>



	about 2: Relay contacts open and close according to item 1				
Proof Test Coverage	See Safety-related characteristics				
	7.4 Test 3: With switch-on pulse checking				
Conditions	<ul> <li>Use of a VEGA transducer with 8/16 mA output</li> <li>Output signals correspond to the current limit level</li> </ul>				
Procedure	1. Press test key				
	2. Check relay contacts				
Expected result	<ul> <li>about 1: State of relay and LED display follows the switch-on pulse (the curve of the switch-on pulse is described in the transducer operating instructions)</li> </ul>				
	about 2: Relay contacts open and close according to item 1				
Proof Test Coverage	See Safety-related characteristics				
SIL	If with VEGATOR121.**S relay 2 is selected as fail safe relay, it can be used to report the test result. This test can be automated with a downstream SSPS.				
	The procedure is described in the operating instructions manual.				



### 8 Appendix A: Test report

Identification	
Company/Tester	
Plant/Instrument TAG	
Meas. loop TAG	
Instrument type/Order code	
Instrument serial number	
Date, setup	
Date, last function test	

Test reason		Test scope	
()	Setup	()	without input current simulation
()	Proof test	()	with input current simulation
		()	with switch-on pulse checking

Mode		Delay times	
Max.	Channel 1 (); channel 2 ()	()	Switch-on delay
Min.	Channel 1 (); channel 2 ()	()	Switch-off delay
()	Range monitoring		

#### Test result for test 1 and 2

Limit level signal Channel 1	Min./Max. switch chan- nel 1	Condition Relay 1	Limit level signal Channel 2	Min./Max. switch chan- nel 2	Condition Relay 2	Test result

#### Test result for test 3

Limit level signal Channel 1	State func- tion test	Condition Relay 1	Limit level signal Channel 2	State func- tion test	Condition Relay 2	Test result
	Fault message			Fault message		
	Empty signal			Empty signal		
	Full signal			Full signal		

Confirmation	
Date:	Signature:



### 9 Appendix B: Term definitions

#### Abbreviations

	~
SIL	Safety Integrity Level (SIL1, SIL2, SIL3, SIL4)
SC	Systematic Capability (SC1, SC2, SC3, SC4)
HFT	Hardware Fault Tolerance
SFF	Safe Failure Fraction
PFD <sub>AVG</sub>	Average Probability of dangerous Failure on Demand
PFH	Average frequency of a dangerous failure per hour (Ed.2)
FMEDA	Failure Mode, Effects and Diagnostics Analysis
FIT	Failure In Time (1 FIT = 1 failure/10 <sup>9</sup> h)
$\lambda_{\text{SD}}$	Rate for safe detected failure
$\lambda_{_{SU}}$	Rate for safe undetected failure
$\lambda_{s}$	$\lambda_{\rm S} = \lambda_{\rm SD} + \lambda_{\rm SU}$
$\lambda_{\text{DD}}$	Rate for dangerous detected failure
$\lambda_{_{DU}}$	Rate for dangerous undetected failure
$\lambda_{_{\!H}}$	Rate for failure, who causes a high output current (> 21 mA)
$\lambda_{L}$	Rate for failure, who causes a low output current ( $\leq$ 3.6 mA)
$\lambda_{_{\!\!AD}}$	Rate for diagnostic failure (detected)
$\lambda_{_{AU}}$	Rate for diagnostic failure (undetected)
DC	Diagnostic Coverage
PTC	Proof Test Coverage (Diagnostic coverage for manual proof tests)
T1	Proof Test Interval
LT	Useful Life Time
MTBF	Mean Time Between Failure = MTTF + MTTR
MTTF	Mean Time To Failure
MTTR	IEC 61508, Ed1: Mean Time To Repair
	IEC 61508, Ed2: Mean Time To Restoration
$MTTF_{d}$	Mean Time To dangerous Failure (ISO 13849-1)
PL	Performance Level (ISO 13849-1)



### 10 Supplement C: SIL conformity

## Certificate



#### Nr./No.: 968/FSP 1025.04/19

Prüfgegenstand Product tested	Auswertgerät VEGATOR Serie 100 Signal conditioning instrument VEGATOR 100 Series	Zertifikats- inhaber Certificate holder	VEGA Grieshaber KG Am Hohenstein 113 77761 Schiltach Germany		
Typbezeichnung Type designation	VEGATOR 121/122 (8/16 mA)				
Prüfgrundlagen Codes and standards	IEC 61508 Parts 1-7:2010 IEC 61511-1:2016+ Corr.1:2016 + AMD1:2017 IEC 61010-1:2017		3-2:2017 1:2007 (in extracts) :2007 (in extracts)		
Bestimmungsgemäße Verwendung Intended application	Die Auswertgeräte der VEGATOR S genannten Prüfgrundlagen und könr				
	The signal conditioning instruments requirements of the stated standards acc. IEC 61508, in HFT=0 configura SIL 3.	s and can be used	in a safety-related system	щ	
Besondere Bedingungen Specific requirements	Die Hinweise in der zugehörigen Installations- und Betriebsanleitung sowie des Sicherheitshandbuchs sind zu beachten. The instructions of the associated Installation, Operating and Safety Manual shall be considered.				
Gültig bis / Valid until 2024-12-	16			ain, 51105 industrie	
vom 16.12.2019 dokumentiert si Dieses Zertifikat ist nur gültig für The issue of this certificate is ba Report No. 968/FSP 1025.01/19	Erzeugnisse, die mit dem Prüfgegensta sed upon an examination, whose results	and übereinstimme s are documented	en.	ÜV Rheinland Industrie Service GmbH, Am Grauen Stein, 51105 Kän / Germany tel: +49 221 806-1790, Fax: +49 221 806-1539, E-Mail: industrie-service@de.tuv.com	
	TÜV Rheinland Industrie Sen Bereich Automation Funktionale Sicherhei		$\alpha \beta \beta$	and Industrie Se 21 806-1790, Fax	
Köln, 2019-12-16	Am Grauen Stein, 51105 F Certification Body Safety & Security for Auto	Köln (	DiplIng. Gebhard Bouwer	TÜV Rheinl Tel.: +49 22	
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#### SIL manufacturer declaration, NE130: Form B.1

Manufacturer										
VEGA Grieshaber KG Am Hohenstein 113 77761 Schiltach, Germany										
General										
Device designation and permissible types	VEGATOR 121, 1	22		Item-No: TC	R12'					
Safety-related output signal	VEGATOR 121: 1: VEGATOR 122: 2:			ptional 1x fa	il safe	e relay output (SPDT)				
Fault current	n/a (in safe stat	e relay is de-ene	ergize	ed)						
Process variable / function	Signal conditioning	g instrument								
Safety function(s)	Transmission of 8/	'16 mA signals for	Point	level detecti	on (N	/IN / MAX / Range)				
Device type acc. to IEC 61508-2	🖾 Туре А			🗌 Туре В						
Operating mode	Low Demand N	lode		🛛 High Dem	nand	or Continuous Mode				
Valid Hardware-Version	≥ 1.1.0									
Valid Software-Version	n/a									
Safety manual	Document ID: 49221									
Type of evaluation (check only one box)	Complete HW/SW evaluation parallel to development incl. FMEDA and change request acc. to IEC 61508-2, 3									
	Evaluation of "Prior use" performance for HW/SW incl. FMEDA and change request acc. to IEC 61508-2, 3									
		Evaluation of HW/SW field data to verify "prior use" acc. to IEC 61511								
	Evaluation by FMEDA acc. to IEC61508-2 for devices without software									
Evaluation through (incl. certificate no.)	TÜV Rheinland Ind	TÜV Rheinland Industry Service GmbH, Nr./No. 968/FSP 1025.04/19								
Test documents	Development documents Test reports Data sheets									
Safety Integrity										
Systematic Capability (SC)			□s	C2 for SIL2		SC3 for SIL3				
Hardware Safety Integrity	Single-channel u	ise (HFT=0)	⊠s	SIL2 capable SIL3 capable						
	Multi-channel us	e (HFT≥1)	□s	] SIL2 capable 🛛 SIL3 capable						
FMEDA	VEGATOR 121			VEGATOR 122						
Safety function(s)	MIN / MAX / Rang	e		MIN / MAX / Range						
) (EIT - Esilves la Tima (40% b)				70 517						

Safety	function(s)	MIN / MAX / Range	MIN / MAX / Range
λdu	(FIT = Failure In Time / 10 <sup>9</sup> h)	49 FIT	79 FIT
$\lambda_{DD}$		30 FIT	45 FIT
λsυ		242 FIT	323 FIT
$\lambda_{SD}$		0 FIT	0 FIT
SFF	(Safe Failure Fraction)	> 60 %	> 60 %
PTC	(Proof Test Coverage)	Test 1: 91% Test 2 and 3: 96%	Test 1: 91% Test 2 and 3: 97%
FMED	A data source	SN 29500	

#### Declaration

49221-EN-200121

Our internal company quality management system ensures information on safety-related systematic faults which become evident in the future.





Printing date:



All statements concerning scope of delivery, application, practical use and operating conditions of the sensors and processing systems correspond to the information available at the time of printing.

Subject to change without prior notice

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